



EQUILIBRIUM OF TOKAMAK PLASMA

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OUTLINE OF LECTURE 3

- **Governing equations**
- **Coordinate transforms**
- **Shafranov and flux coordinates**
- **Grad-Shafranov equation**
- **Summary**

GOVERNING IDEAL MHD EQUATIONS FOR PLASMA - 1

- For describing *plasma particles*, we take velocity moments of the kinetic equations for electron and thermal ion distribution functions and obtain

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{V}) = 0;$$

$$\rho \frac{d\mathbf{V}}{dt} = -\nabla p + \frac{1}{c} \mathbf{J} \times \mathbf{B};$$

$$\frac{\partial p}{\partial t} + \mathbf{V} \cdot \nabla p + \gamma p \nabla \cdot \mathbf{V} = 0;$$

$$\mathbf{E} + \frac{1}{c} \mathbf{V} \times \mathbf{B} = 0;$$

- For describing *electromagnetic fields* in the plasma, Maxwell's equations are used

$$\nabla \times \mathbf{B} = \frac{4\pi}{c} \mathbf{J}$$

$$\nabla \times \mathbf{E} = -\frac{1}{c} \frac{\partial \mathbf{B}}{\partial t}$$

$$\nabla \cdot \mathbf{B} = 0$$

- Here, scale lengths larger than Debye length are considered with $n_e = \sum_i Z_i \cdot n_i$

GOVERNING IDEAL MHD EQUATIONS FOR PLASMA - 2

- Express plasma current as sum of components parallel and perpendicular to magnetic field:

$$\mathbf{J} = \frac{(\mathbf{J} \cdot \mathbf{B})}{B^2} \mathbf{B} + \frac{\mathbf{B} \times (\mathbf{J} \times \mathbf{B})}{B^2}$$

- The second term is taken from the equation of motion

$$\rho \frac{d\mathbf{V}}{dt} = -\nabla p + \frac{1}{c} \mathbf{J} \times \mathbf{B} \quad \rightarrow \quad \frac{1}{c} \mathbf{B} \times (\mathbf{J} \times \mathbf{B}) = \left(\mathbf{B} \times \rho \frac{d\mathbf{V}}{dt} \right) + (\mathbf{B} \times \nabla p)$$

- From Amperes law we have that

$$\nabla \cdot \mathbf{J} = \nabla \cdot \left(\frac{c}{4\pi} \nabla \times \mathbf{B} \right) = 0$$

- Substituting first two equations in the third and using a vector identity and $\nabla \cdot \mathbf{B} = 0$ we arrive at the main governing equation of Ideal MHD

$$\mathbf{B} \cdot \nabla \left(\frac{\mathbf{J} \cdot \mathbf{B}}{B^2} \right) + \nabla \cdot \left(4\pi \rho \frac{\mathbf{B} \times d\mathbf{V} / dt}{B^2} \right) + \nabla \cdot \left(\frac{\mathbf{B} \times \nabla p}{B^2} \right) = 0$$

GOVERNING IDEAL MHD EQUATIONS FOR PLASMA - 3

- We introduce equilibrium (denoted by subscript 0) and perturbed (denoted by δ) quantities and let $\mathbf{v}_0 = 0$, i.e.

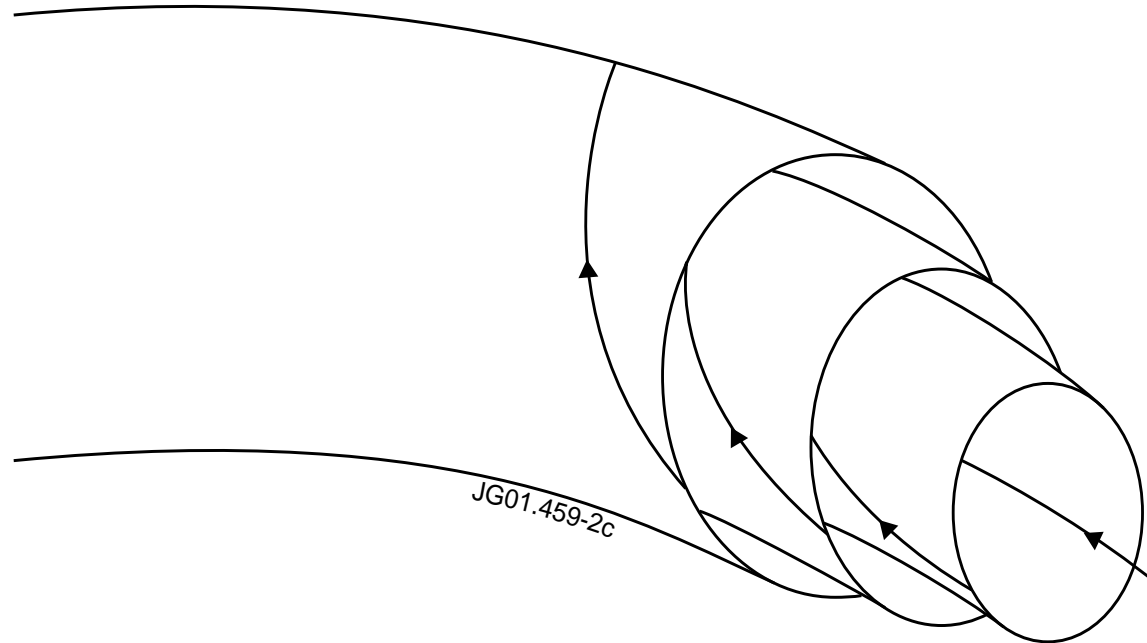
$$\mathbf{J} = \mathbf{J}_0 + \delta\mathbf{J}, \quad \mathbf{B} = \mathbf{B}_0 + \delta\mathbf{B}, \quad \mathbf{V} = \delta\mathbf{V}, \quad p = p_0 + \delta p$$

- Static equilibrium means $d/dt = 0$, so we get the following equation for the equilibrium

$$\nabla p_0 = \frac{1}{c} \mathbf{J}_0 \times \mathbf{B}_0$$

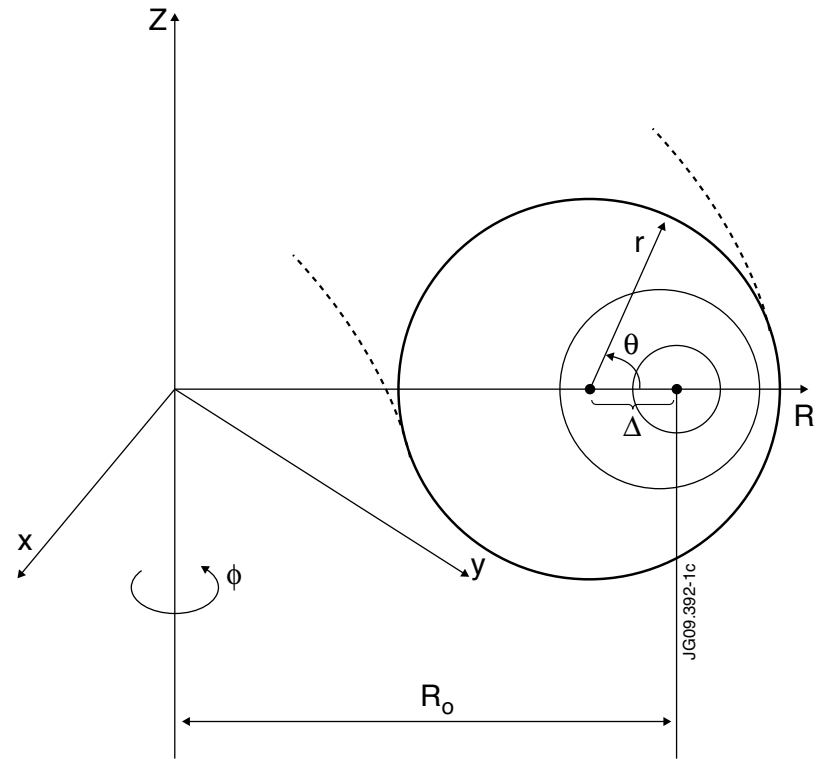
- It follows then that $\mathbf{B}_0 \nabla p_0 = 0$, $\mathbf{J}_0 \nabla p_0 = 0$, i.e. plasma pressure is constant along magnetic field lines and along the current lines; the plasma may expand freely along these lines
- Since ∇p_0 is perpendicular to the surface $p_0 = \text{const}$, the magnetic field lines and the current lines must lie on the $p_0 = \text{const}$ surfaces
- Toroidal surfaces enclosed within each other perfectly fit all the conditions above \rightarrow torus

GOVERNING IDEAL MHD EQUATIONS FOR PLASMA - 4



$$B = B_0(1 - (r/R)\cos\vartheta)$$

WHAT COORDINATES ARE BEST FOR DESCRIBING EQUILIBRIUM?



$$\nabla p_0 = \frac{1}{c} \mathbf{J}_0 \times \mathbf{B}_0$$

COORDINATE TRANSFORMS - 1

- Begin with **Cartesian coordinates** (x, y, z)
- Basis of unit vectors = $(\mathbf{e}_x, \mathbf{e}_y, \mathbf{e}_z)$
- Representation of a vector:

$$\mathbf{A} = x\mathbf{e}_x + y\mathbf{e}_y + z\mathbf{e}_z$$

- Components of a vector:

$$x = (\mathbf{e}_y \times \mathbf{e}_z) \cdot \mathbf{A}; \quad y = (\mathbf{e}_z \times \mathbf{e}_x) \cdot \mathbf{A}; \quad z = (\mathbf{e}_x \times \mathbf{e}_y) \cdot \mathbf{A}$$

- If transform to another coordinate system (α, β, γ) , then

$$\mathbf{A} = \alpha\mathbf{e}_\alpha + \beta\mathbf{e}_\beta + \gamma\mathbf{e}_\gamma, \text{ with}$$

$$\alpha = x \frac{\partial x}{\partial \alpha} + y \frac{\partial y}{\partial \alpha} + z \frac{\partial z}{\partial \alpha}, \quad \beta = x \frac{\partial x}{\partial \beta} + y \frac{\partial y}{\partial \beta} + z \frac{\partial z}{\partial \beta}, \quad \gamma = x \frac{\partial x}{\partial \gamma} + y \frac{\partial y}{\partial \gamma} + z \frac{\partial z}{\partial \gamma}.$$

COORDINATE TRANSFORMS - 2

- Define **curvilinear coordinates** (ξ^1, ξ^2, ξ^3)
- **Covariant basis** $= (\nabla \xi^1, \nabla \xi^2, \nabla \xi^3)$
- Covariant representation of a vector: $\mathbf{A} = A_1 \nabla \xi^1 + A_2 \nabla \xi^2 + A_3 \nabla \xi^3$
- Covariant components of a vector:

$$A_1 = J(\nabla \xi^2 \times \nabla \xi^3) \cdot \mathbf{A}; \quad A_2 = J(\nabla \xi^3 \times \nabla \xi^1) \cdot \mathbf{A}; \quad A_3 = J(\nabla \xi^1 \times \nabla \xi^2) \cdot \mathbf{A}$$

where Jacobian J is given by $J = [(\nabla \xi^1 \times \nabla \xi^2) \cdot \nabla \xi^3]^{-1}$

- Substitute:

$$\mathbf{A} = \frac{(\nabla \xi^2 \times \nabla \xi^3) \cdot \mathbf{A}}{(\nabla \xi^1 \times \nabla \xi^2) \cdot \nabla \xi^3} \nabla \xi^1 + \frac{(\nabla \xi^3 \times \nabla \xi^1) \cdot \mathbf{A}}{(\nabla \xi^1 \times \nabla \xi^2) \cdot \nabla \xi^3} \nabla \xi^2 + \frac{(\nabla \xi^1 \times \nabla \xi^2) \cdot \mathbf{A}}{(\nabla \xi^1 \times \nabla \xi^2) \cdot \nabla \xi^3} \nabla \xi^3$$

- If transform to another coordinate system $(\tilde{\xi}^1, \tilde{\xi}^2, \tilde{\xi}^3)$, then

$$\mathbf{A} = \tilde{A}_1 \nabla \tilde{\xi}^1 + \tilde{A}_2 \nabla \tilde{\xi}^2 + \tilde{A}_3 \nabla \tilde{\xi}^3, \text{ with}$$

$$\tilde{A}_i = \sum_j A_j \frac{\partial \xi^j}{\partial \tilde{\xi}^i}$$

COORDINATE TRANSFORMS – 3

- **Contravariant basis** = $(J(\nabla \xi^2 \times \nabla \xi^3), J(\nabla \xi^3 \times \nabla \xi^1), J(\nabla \xi^1 \times \nabla \xi^2))$
- **Contravariant components:** $A^1 = \mathbf{A} \cdot \nabla \xi^1$, $A^2 = \mathbf{A} \cdot \nabla \xi^2$, $A^3 = \mathbf{A} \cdot \nabla \xi^3$
- **Substitute:**

$$\mathbf{A} = \mathbf{A} \cdot \nabla \xi^1 \frac{(\nabla \xi^2 \times \nabla \xi^3)}{(\nabla \xi^1 \times \nabla \xi^2) \cdot \nabla \xi^3} + \mathbf{A} \cdot \nabla \xi^2 \frac{(\nabla \xi^3 \times \nabla \xi^1)}{(\nabla \xi^1 \times \nabla \xi^2) \cdot \nabla \xi^3} + \mathbf{A} \cdot \nabla \xi^3 \frac{(\nabla \xi^1 \times \nabla \xi^2)}{(\nabla \xi^1 \times \nabla \xi^2) \cdot \nabla \xi^3}$$

- **Metric tensor is relationship between covariant and contravariant components:**

$$A^i = \sum_j A_j \nabla \xi^j \cdot \nabla \xi^i = \sum_j g^{ij} A_j,$$

where the contravariant components of tensor \mathbf{g} are given by

$$g^{ij} = \nabla \xi^i \cdot \nabla \xi^j = \frac{\partial \xi^i}{\partial x} \cdot \frac{\partial \xi^j}{\partial x} + \frac{\partial \xi^i}{\partial y} \cdot \frac{\partial \xi^j}{\partial y} + \frac{\partial \xi^i}{\partial z} \cdot \frac{\partial \xi^j}{\partial z}$$

- **Covariant components of tensor \mathbf{g} are given by the inverse matrix:**

$$g_{ij} = [g^{ij}]^{-1} = \frac{\partial x}{\partial \xi^i} \cdot \frac{\partial x}{\partial \xi^j} + \frac{\partial y}{\partial \xi^i} \cdot \frac{\partial y}{\partial \xi^j} + \frac{\partial z}{\partial \xi^i} \cdot \frac{\partial z}{\partial \xi^j}$$

$$\text{Det}(g_{ij}) \equiv g = J^2$$

COORDINATE TRANSFORMS - 4

- Volume element:

$$d^3x = dx dy dz = J d\xi^1 d\xi^2 d\xi^3$$

- Length element:

$$(ds)^2 = (dx)^2 + (dy)^2 + (dz)^2 = \sum_{i,j=1}^3 g_{ij} d\xi^i d\xi^j$$

- Divergence:

$$\nabla \cdot \mathbf{A} = \frac{1}{J} \frac{\partial}{\partial \xi^i} (J A^i)$$

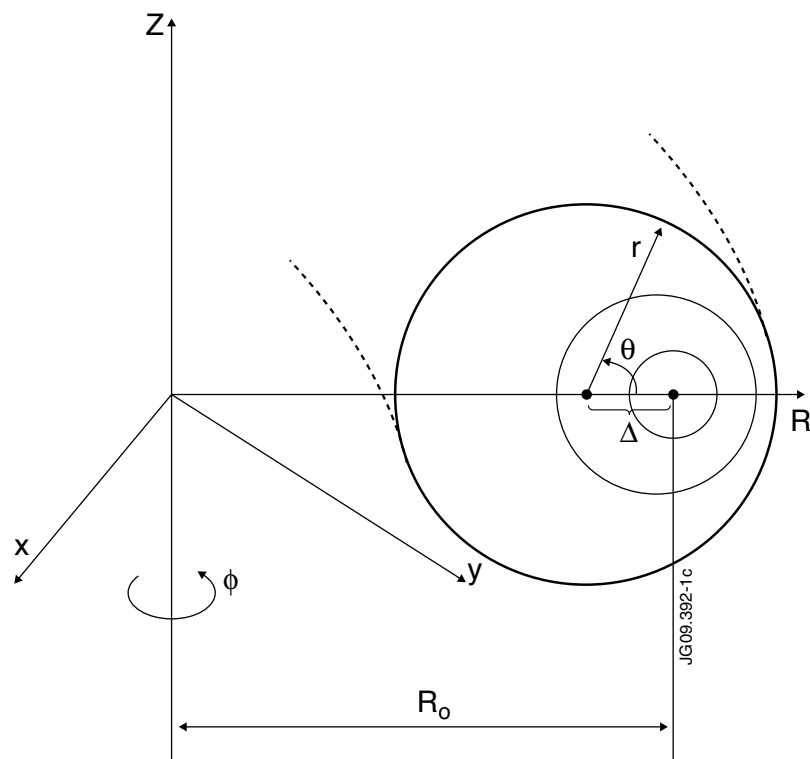
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$$(\nabla \times \mathbf{A})^i = \nabla^{\xi^i} \cdot \sum_{j,m} \nabla^{\xi^j} \times \left(\frac{\partial}{\partial \xi^j} \nabla^{\xi^m} A_m \right) = \frac{1}{J} \sum_{j,k} \varepsilon_{ijk} \frac{\partial A_k}{\partial \xi^j}$$

where ε_{ijk} is antisymmetric unit matrix whose only non-zero components are

$$\varepsilon_{123} = \varepsilon_{231} = \varepsilon_{312} = 1; \quad \varepsilon_{132} = \varepsilon_{213} = \varepsilon_{321} = -1$$

SHAFRANOV COORDINATES – 1



$$R = R_0 + r \cos \mathcal{G} - \Delta(r)$$

$$= \sqrt{x^2 + y^2};$$

$$\phi = -\zeta$$

$$= \tan^{-1}(y/x);$$

$$Z = r \sin \mathcal{G};$$

Inversed relations:

$$x = R \cos \phi = R \cos \zeta;$$

$$y = R \sin \phi = -R \sin \zeta$$

SHAFRANOV COORDINATES – 2

- Transformation matrix from (x, y, Z) to $(\xi^1 = r, \xi^2 = \vartheta, \xi^3 = \zeta)$:

$$\begin{array}{lll}
 \frac{\partial x}{\partial r} = \left(\frac{\partial R}{\partial r}\right) \cos \zeta & \frac{\partial x}{\partial \vartheta} = \left(\frac{\partial R}{\partial \vartheta}\right) \cos \zeta & \frac{\partial x}{\partial \zeta} = -R \sin \zeta \\
 \frac{\partial y}{\partial r} = -\left(\frac{\partial R}{\partial r}\right) \sin \zeta & \frac{\partial y}{\partial \vartheta} = -\left(\frac{\partial R}{\partial \vartheta}\right) \sin \zeta & \frac{\partial y}{\partial \zeta} = -R \cos \zeta \\
 \frac{\partial Z}{\partial r} = \sin \vartheta & \frac{\partial Z}{\partial \vartheta} = r \cos \vartheta & \frac{\partial Z}{\partial \zeta} = 0
 \end{array}$$

so that the covariant components of the metric tensor

$$g_{ij} = \frac{\partial x}{\partial \xi^i} \cdot \frac{\partial x}{\partial \xi^j} + \frac{\partial y}{\partial \xi^i} \cdot \frac{\partial y}{\partial \xi^j} + \frac{\partial z}{\partial \xi^i} \cdot \frac{\partial z}{\partial \xi^j}$$

are given by, e.g. for g_{11} :

$$g_{11} = \left(\frac{\partial R}{\partial r}\right)^2 + \sin^2 \vartheta = (\cos \vartheta - \Delta')^2 + \sin^2 \vartheta = 1 - 2\Delta' \cos \vartheta + \Delta'^2$$

SHAFRANOV COORDINATES – 3

$$g_{ij} = \begin{pmatrix} 1 - 2\Delta' \cos \vartheta + \Delta'^2 & r\Delta' \sin \vartheta & 0 \\ r\Delta' \sin \vartheta & r^2 & 0 \\ 0 & 0 & R^2 \end{pmatrix}$$

and we obtain *Shafranov's Jacobian* as

$$J_S = \sqrt{\det(g_{ij})} = rR \cdot (1 - \Delta' \cos \vartheta) \cong rR_0 \cdot \left(1 + \left(\frac{r}{R_0} - \Delta' \right) \cdot \cos \vartheta \right)$$

where we used the large aspect ratio ordering

$$\Delta / R_0 \cong \varepsilon^2 \ll \varepsilon = (r / R_0) \ll 1$$

SHAFRANOV COORDINATES – 4

- We also need the contravariant metric elements. These can be found from

$$g^{ij} = (g_{ij})^{-1} = \frac{1}{J^2} \begin{pmatrix} g_{22} \cdot g_{33} & -g_{12} \cdot g_{33} & 0 \\ -g_{12} \cdot g_{33} & g_{11} \cdot g_{33} & 0 \\ 0 & 0 & g_{11} \cdot g_{22} - g_{12}^2 \end{pmatrix}$$

- These contravariant elements are:

$$g^{11} = \nabla r \cdot \nabla r = 1 + 2\Delta' \cos \vartheta$$

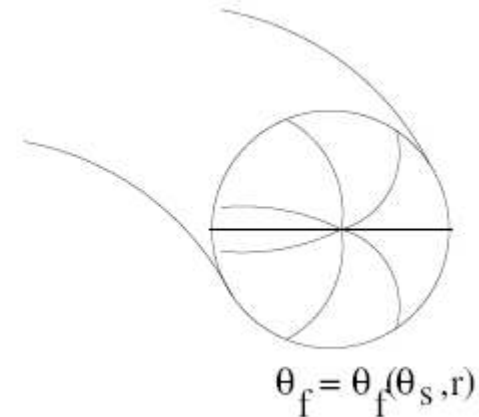
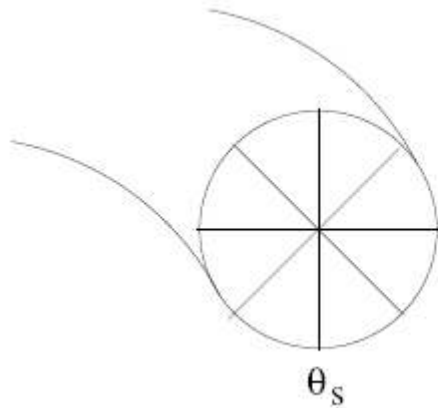
$$g^{12} = \nabla r \cdot \nabla \vartheta = -\frac{1}{r} \Delta' \sin \vartheta$$

$$g^{22} = \nabla \vartheta \cdot \nabla \vartheta = \frac{1}{r^2}$$

$$g^{33} = \nabla \zeta \cdot \nabla \zeta = \frac{1}{R^2}$$

FLUX-TYPE COORDINATES – 1

- Now, we want to introduce safety factor $q = \frac{\mathbf{B} \cdot \nabla \zeta}{\mathbf{B} \cdot \nabla \vartheta}$ which would be ϑ -*independent*
- Since the ‘density’ of magnetic field lines is higher in the inner side of the torus, a different poloidal coordinate than the usual poloidal angle is required.



- Searching for a good set of *flux-type* coordinates $(r_f; \vartheta_f; \zeta_f)$ related to *Shafranov* coordinates $(r_s; \vartheta_s; \zeta_s)$ via

$$r_f = r_s; \quad \vartheta_f = \vartheta_f(r_f, \vartheta_s); \quad \zeta_f = \zeta_s$$

FLUX-TYPE COORDINATES – 2

- The expression for ϑ_f is found from the condition $\partial q / \partial \vartheta_f = 0$ as follows:
- Split \mathbf{B} into poloidal and toroidal parts, $\mathbf{B} = \nabla \zeta \times \nabla \psi + I(\psi) \nabla \zeta$ and see:

$$(\nabla \zeta)^2 = (1/R)^2 \rightarrow \mathbf{B} \cdot \nabla \zeta_f = I(\psi) / R^2$$

$$\nabla \psi = (d\psi / dr) \nabla r \rightarrow \mathbf{B} \cdot \nabla \vartheta_f = \frac{d\psi}{dr} \cdot \left(\frac{1}{\nabla r_f \times \nabla \vartheta_f \cdot \nabla \zeta_f} \right)^{-1} = \frac{\psi'}{J_f}, \text{ where } J_f = 1 / (\nabla r_f \times \nabla \vartheta_f \cdot \nabla \zeta_f)$$

- Require $q = \frac{\mathbf{B} \cdot \nabla \zeta}{\mathbf{B} \cdot \nabla \vartheta} = q(\psi)$, obtain $J_f = \frac{R^2(r, \vartheta) \cdot q(\psi) \psi'}{I(\psi)}$, with ϑ only involved in R^2
- On the other hand, the ratio of the Jacobians gives differential equation of the poloidal angle variables. So we can find the flux-type angle via Shafranov angle:

$$\frac{\partial \vartheta_f}{\partial \vartheta_s} = \frac{J_s}{J_f} \propto \frac{1 + ((r/R_0) - \Delta') \cos \vartheta_s}{1 + 2(r/R_0) \cos \vartheta_s} \cong 1 - \left(\frac{r}{R_0} + \Delta' \right) \cos \vartheta_s,$$



FLUX-TYPE COORDINATES – 3

$$\vartheta_f = \vartheta_s - \left(\frac{r}{R_0} + \Delta' \right) \sin \vartheta_s + C$$

Here, $C = 0$ since ϑ_f must change by 2π whenever ϑ_s does.

- Inverting the expression for $\vartheta_f(r_f, \vartheta_s)$ gives

$$\vartheta_s = \vartheta_f + \left(\frac{r}{R_0} + \Delta' \right) \sin \vartheta_f$$

and we can write using Taylor expansions:

$$\begin{aligned} \cos \vartheta_s &\cong \cos \vartheta_f + \left(\frac{r}{R_0} + \Delta' \right) \sin \vartheta_f \cdot (-\sin \vartheta_f) = \cos \vartheta_f - \eta(r)(1 - \cos 2\vartheta_f); \\ \sin \vartheta_s &\cong \sin \vartheta_f + \left(\frac{r}{R_0} + \Delta' \right) \sin \vartheta_f \cdot (+\cos \vartheta_f) = \sin \vartheta_f + \eta(r) \sin 2\vartheta_f; \end{aligned}$$

where $\eta(r) \cong \frac{1}{2} \left(\frac{r}{R_0} + \Delta' \right)$

- We can now re-write Shafranov coordinates to get flux-type coordinates:

$$R = R_0 + r \cos \vartheta_f - \Delta(r) - r\eta(r)(1 - \cos 2\vartheta_f); \quad \phi = -\zeta; \quad Z = r \sin \vartheta_f + r\eta(r) \sin 2\vartheta_f$$

- The flux-type Jacobian is $J_f = \sqrt{\det(g_{ij}^f)} \cong rR \sqrt{1 + 2 \frac{r}{R_0} \cos \vartheta_f} \cong \frac{rR^2}{R_0}$

FLUX-TYPE COORDINATES – 4

- With the flux-type coordinates we get the covariant matrix (put $\vartheta_f = \vartheta$ here):

$$g_{ij}^f = \begin{pmatrix} 1 - 2\Delta' \cos \vartheta & r \left((r/R_0) \sin \vartheta + (r\Delta')' \sin \vartheta \right) & 0 \\ r \left((r/R_0) \sin \vartheta + (r\Delta')' \sin \vartheta \right) & r^2 (1 + 4\eta \cos \vartheta + 4\eta^2) & 0 \\ 0 & 0 & R^2 \end{pmatrix}$$

- The contravariant elements are:

$$g^{11} = \nabla r \cdot \nabla r = 1 + 2\Delta' \cos \vartheta$$

$$g^{12} = \nabla r \cdot \nabla \vartheta = -\frac{1}{r} \left(\frac{r}{R_0} + (r\Delta')' \right) \sin \vartheta$$

$$g^{22} = \nabla \vartheta \cdot \nabla \vartheta = \frac{1}{r^2} \left(1 - 2 \left(\frac{r}{R_0} + \Delta' \right) \cos \vartheta \right)$$

$$g^{33} = \nabla \zeta \cdot \nabla \zeta = \frac{1}{R^2} = \frac{1}{R_0^2} \left(1 - 2 \frac{r}{R_0} \cos \vartheta \right)$$

GRAD-SHAFRANOV EQUATION – 1

- For solving the equilibrium equation we introduce the poloidal magnetic field flux function ψ and the poloidal current density flux function I :

$$\mathbf{B}_g = \frac{1}{R} [\nabla \psi \times \mathbf{e}_\phi]; \quad \mathbf{J}_g = \frac{2}{cR} [\nabla I \times \mathbf{e}_\phi]$$

- The equilibrium equation $\mathbf{J}_g \times \mathbf{e}_\phi B_\phi + \mathbf{J}_\phi \times \mathbf{e}_\phi B_g = c \nabla p$ takes the form of **Grad-Shafranov equation** then for the poloidal flux ψ :

$$R^2 \nabla \cdot \left(\frac{1}{R^2} \nabla \psi \right) + I \frac{dI}{d\psi} + 4\pi R^2 \frac{dp}{d\psi} = 0, \text{ where (put } \vartheta_f = \vartheta \text{ here):}$$

$$R^2 \nabla \cdot \left(\frac{1}{R^2} \nabla \psi \right) = \frac{R^2}{J} \frac{\partial}{\partial r} \left(\frac{J}{R^2} \psi' g^{11} \right) + \frac{R^2}{J} \frac{\partial}{\partial \vartheta} \left(\frac{J}{R^2} \psi' g^{12} \right) = \frac{1}{r} \frac{\partial}{\partial r} (r \psi') + \cos \vartheta \left(\frac{1}{r} \frac{\partial}{\partial r} (2\Delta' r \psi') - \frac{1}{r} \left(\frac{r}{R_0} + (r\Delta')' \right) \psi' \right),$$

$$I \frac{dI}{d\psi} = I \frac{dI}{dr} \left(\frac{d\psi}{dr} \right)^{-1}, \quad 4\pi R^2 \frac{dp}{d\psi} = \left(\frac{4\pi R_0^2}{\psi'} \right) p' \left(1 + 2 \frac{r}{R_0} \cos \vartheta \right)$$

GRAD-SHAFRANOV EQUATION - 2

- Combining \mathcal{G} - independent terms first:

$$\frac{1}{r}(r\psi')' + \frac{II'}{\psi'} + \frac{4\pi R_0^2}{\psi'} p' = 0 \rightarrow \frac{1}{q}\left(\frac{r^2}{q}\right)' + \frac{II'}{B_0^2} + \frac{4\pi R_0^2}{B_0^2} p' = 0$$

where the safety factor q was introduced from $\psi' = rB_T / q \cong rB_0 / q$

- Thus, only **TWO of the three flux quantities** q , I , and p may be specified **independently**

GRAD-SHAFRANOV EQUATION – 3

- Combining terms $\propto \cos \mathcal{G}$ then:

$$\frac{1}{r} (2r\Delta' \psi')' - \frac{1}{r} \psi' \left(\frac{r}{R_0} + (r\Delta')' \right) + \frac{2r}{R_0} \frac{4\pi R_0^2}{\psi'} p' = 0 \quad \rightarrow \quad (r\Delta' \psi'^2)' = \frac{r}{R_0} (\psi'^2 - 8\pi r R_0^2 p')$$

- Solving this equation for the Shafranov shift, we obtain:

$$\Delta' = \frac{1}{r^2 \psi'^2} \cdot \frac{r}{R_0} \int_0^r r dr (\psi'^2 - 8\pi r R_0^2 p') = \frac{r}{R_0} \left(\frac{\langle \psi'^2 \rangle}{2\psi'^2} - \frac{8\pi R_0^2}{\psi'^2} (p - \langle p \rangle) \right) = \frac{r}{R_0} \left(\frac{\langle B_p^2 \rangle}{2B_p^2} + \frac{8\pi}{B_p^2} (\langle p \rangle - p) \right)$$

where $\langle p \rangle \equiv \frac{2}{r^2} \int_0^r r dr \cdot p(r)$

- Introduce internal inductance $l_i = \langle B_p^2 \rangle / B_p^2$ and poloidal beta $\beta_p = \frac{8\pi}{B_p^2} (\langle p \rangle - p)$ to obtain

$$\Delta' = \frac{r}{R_0} \left(\frac{l_i}{2} + \beta_p \right)$$

TYPICAL JET EQUILIBRIUM

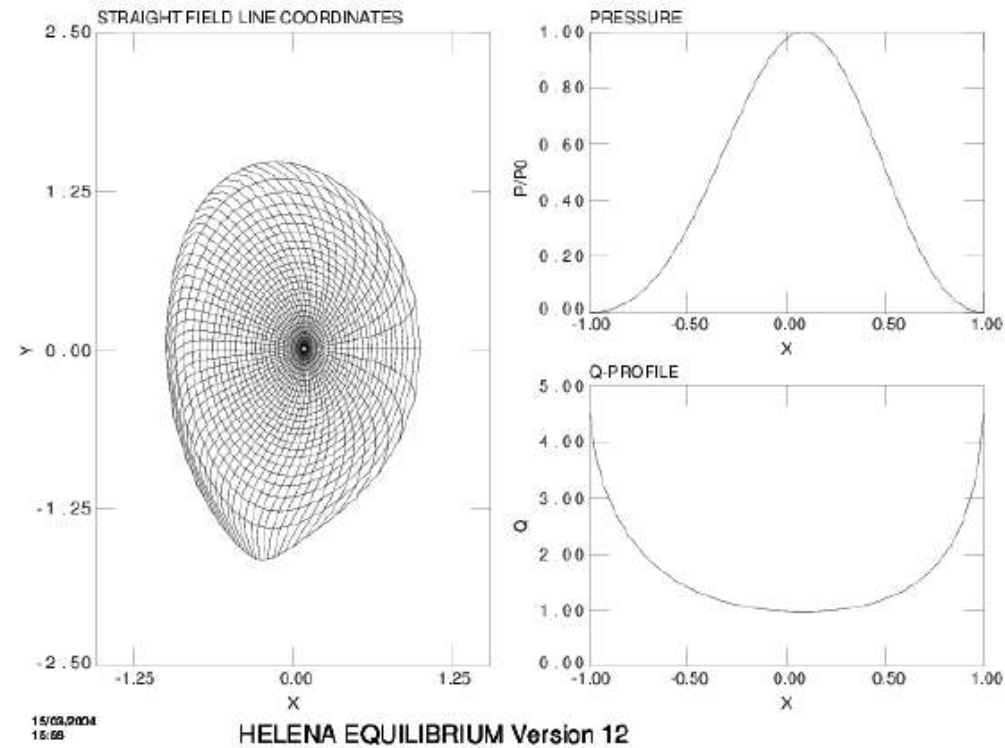


Figure 6: A typical output page from HELENA. $X = (R - R_0)/a$, $Y = z/a$. Left: Equilibrium magnetic flux structure. Upper right: Equilibrium pressure profile. Lower right: q-profile.

SUMMARY

- Plasma equilibrium is governed by equation $\nabla p_0 = \frac{1}{c} \mathbf{J}_0 \times \mathbf{B}_0$ which gives $\mathbf{B}_0 \nabla p_0 = 0$, $\mathbf{J}_0 \nabla p_0 = 0$, i.e. plasma pressure is constant along magnetic field lines and along the current lines; the plasma may expand freely along these lines
- Since ∇p_0 is perpendicular to the surface $p_0 = \text{const}$, the magnetic field lines and the current lines must lie on the $p_0 = \text{const}$ surfaces
- Shafranov coordinates and flux-type coordinates differ by the poloidal angle variable. The approximate relation is $\vartheta_s = \vartheta_f + \left(\frac{r}{R_0} + \Delta' \right) \sin \vartheta_f$
- Grad-Shafranov equation has the form $R^2 \nabla \cdot \left(\frac{1}{R^2} \nabla \psi \right) + I \frac{dI}{d\psi} + 4\pi R^2 \frac{dp}{d\psi} = 0$
- Only two of the three flux quantities q , I , and p may be specified independently
- The internal inductance $l_i = \langle B_p^2 \rangle / B_p^2$ and poloidal beta $\beta_p = \frac{8\pi}{B_p^2} (\langle p \rangle - p)$ determine Δ' as

$$\Delta' = \frac{r}{R_0} \left(\frac{l_i}{2} + \beta_p \right)$$